

PATENT COOPERATION TREATY



PCT

INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

(Chapter II of the Patent Cooperation Treaty)

(PCT Article 36 and Rule 70)

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Applicant				
			SK LTD.	
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Box No. VII	Certain defects in the	he international ar	plication	
Box No. VIII	Certain observation	s on the internation	nal application	
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INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

International application No.

PCT/JP2003/015166

Box No. I	Basis of the report	PCT/JP2003/015166
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INTERNATIONAL PRELIMINARY EXAMINATION REPORT

Internation application No.
PCT/JP 03/15166

v.	Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement
	- and bearing own street tell

Statement			
Novelty (N)	Claims	1-18	YES
	Claims		NO
Inventive step (IS)	Claims	2, 3	YES
	Claims	1, 4-18	NO
Industrial applicability (IA)	Claims	1-18	YES
	Claims		NO

Citations and explanations

Document 1: JP 8-294299 A (Matsushita Electric Industrial Co., Ltd.), 5 November 1996, all pages, & US 5701066 A

Document 2: JP 2000-270599 A (Yaskawa Electric Corp.), 29 September 2000, all pages (Family: none)

Document 3: JP 11-55994 A (Yaskawa Electric Corp.), 26 February 1999, all pages (Family: none)

Document 4: JP 9-23699 A (Yamaha Motor Co., Ltd.), 21
January 1997, all pages (Family: none)

Document 1 discloses a motor drive control device wherein a motor current is detected, and current control for a three-phase AC motor is performed using vector control. Further, document 1 also discloses the use of the motor control device in an electrically-powered power steering device.

Document 2 discloses an AC motor control device that performs PI control when controlling current.

Document 3 discloses a brushless DC motor control device for performing control wherein the motor terminal voltage has a square waveform. Further, document 3 also discloses sensorless drive.

Document 4 discloses a permanent magnet synchronous motor control device which performs control in a manner

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characterized in that when performing weak field control in a high-speed range, the field current strength is calculated from the torque and the speed, and at or above a specified speed, the field current is progressively reduced in alignment with the speed, thereby preventing excessive rotation.

Claims 1, 4, and 7 do not involve an inventive step in the light of documents 1 and 2.

Claims 5 and 6 do not involve an inventive step in the light of documents 1 to 3.

Claims 8 to 13 do not involve an inventive step in the light of documents 3 and 4. A person skilled in the art could easily conceive of applying square waveform control such as that disclosed in document 3 to the motor control device for performing weak field control disclosed in document 4.

Claims 14 to 18 do not involve an inventive step in the light of documents 3 and 4. The reduction of harmonic waves is merely a feature fittingly implemented by a person skilled in the art.

Claims 2 and 3 are novel and involve an inventive step. The characterizing features of the invention described in claim 2 are neither disclosed nor suggested in any of the documents, nor would they be obvious to a person skilled in the art.

Claims 1 to 18 are clearly industrially applicable.